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Research Article

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SuperdropNet: A Stable and Accurate Machine Learning Proxy for Droplet-Based Cloud Microphysics

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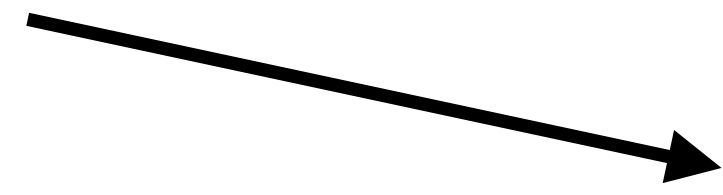
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 **VIEW METRICS**

Celeste Tong

ML Journal Club 2026.4.30

Autoregressive emulator



forward operator

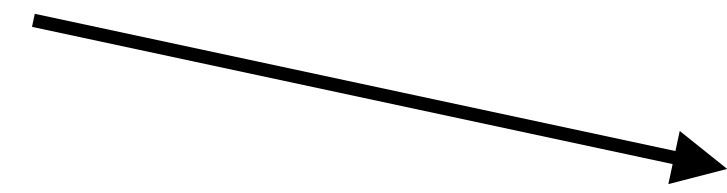
stochasticity

$$y = Hx + n$$

Cloud microphysics at $t+\Delta t$

Cloud microphysics at t

Autoregressive emulator



forward operator

stochasticity

$$y = Hx + n$$

Cloud microphysics at $t+\Delta t$

Cloud microphysics at t

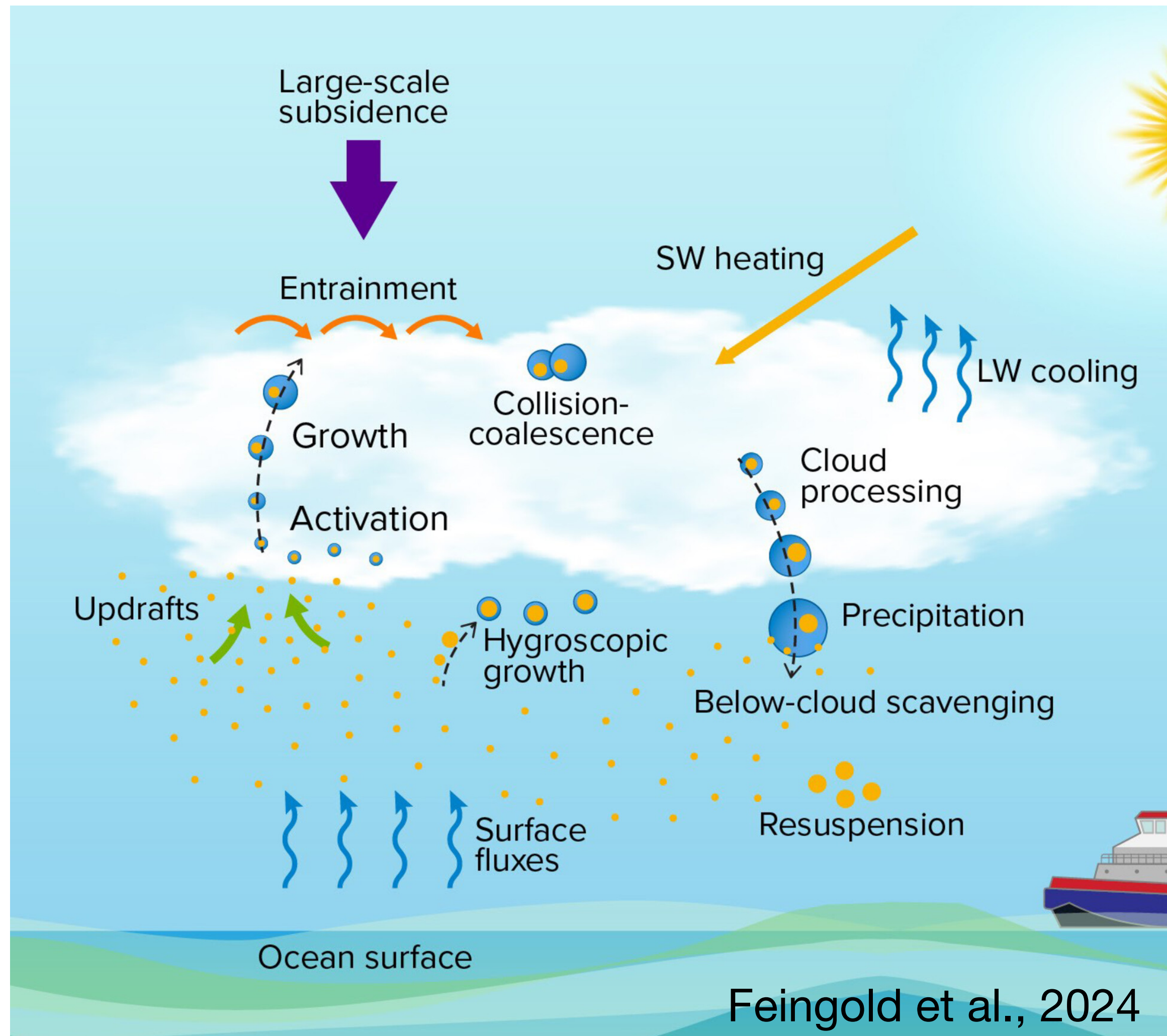
Cloud microphysics:

- What and why?
- Current approaches
 - Bulk scheme
 - Super droplet simulations (SDS)

Cloud microphysics: small-scale interactions between water vapor, aerosols, liquid droplets, ice crystals, and precipitation particles

- Sub-micron to cm scale
- Evolution of the particle size distribution
 - Mass(t)
 - Concentration(t)
 - Hydrometeor state (t)
- Importance
 - Radiation: albedo and lifetime
 - Weather: amount, timing, type of precipitation

Cloud microphysics: small-scale interactions between water vapor, aerosols, liquid droplets, ice crystals, and precipitation particles

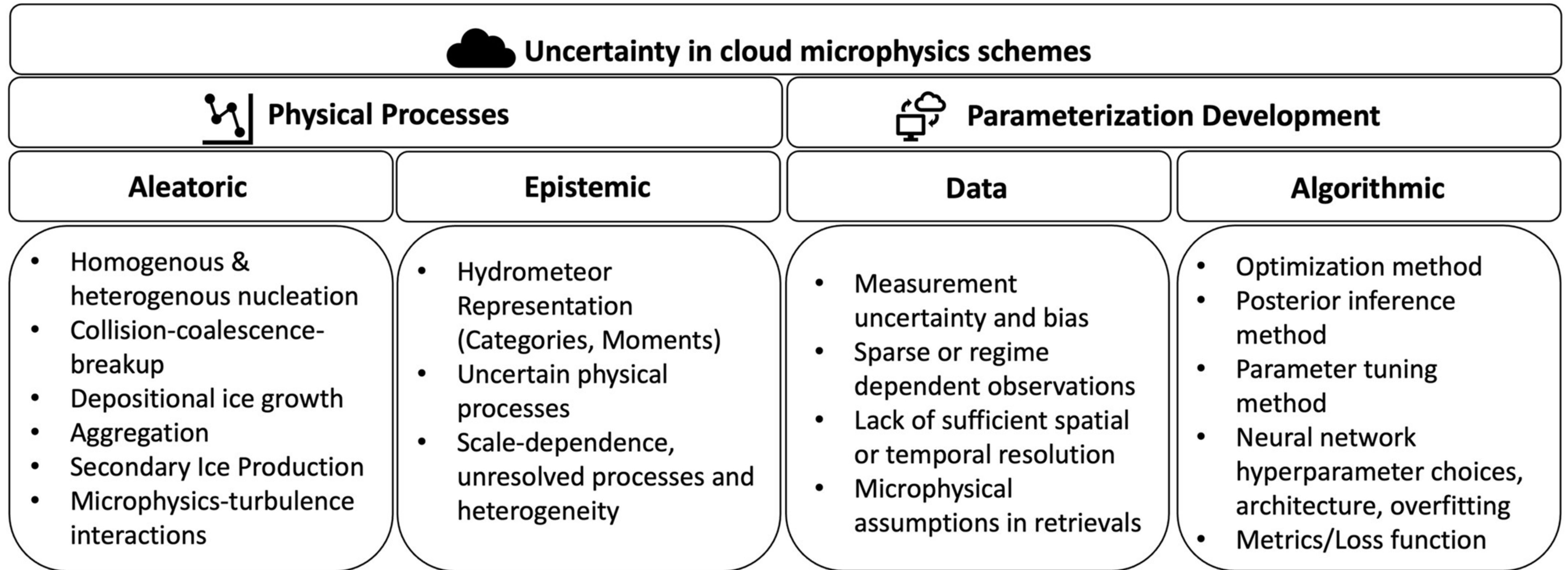


Processes:

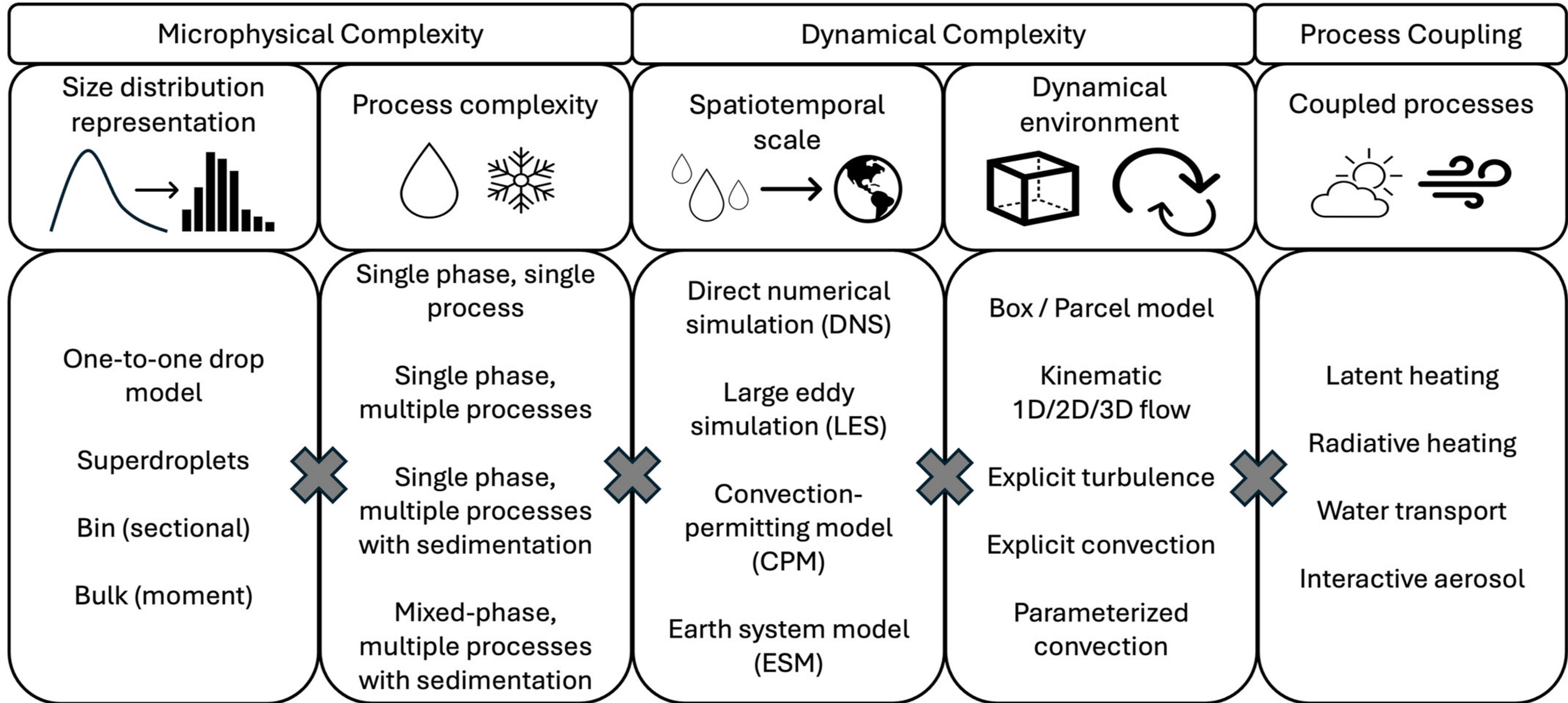
- Nucleation/activation: aerosols
- Condensation/evaporation: droplet growth/shrinkage by vapor diffusion
- Autoconversion: small cloud droplets colliding to form raindrops
- Accretion: rain collecting cloud droplets
- Self-collection: droplets/drops colliding with same-category particles
- Sedimentation: gravitational settling

and MANY more if there is ice!

Challenges of Cloud Microphysics Scheme Development



Modeling Complexity



Bulk Moment Schemes (warm rain)

- Tracking the 0th and 1st moments of droplet distribution

L: total mass (1st moment)

N: # concentration (0th moment)

$$\begin{aligned} L_c &= \int_0^{x^*} xf(x)dx & N_c &= \int_0^{x^*} f(x)dx \\ L_r &= \int_{x^*}^{\infty} xf(x)dx & N_r &= \int_{x^*}^{\infty} f(x)dx \end{aligned} \tag{1}$$

c: cloud; r: rain

f(x): density function of droplets with mass x

Two Moment Bulk Scheme (warm rain)

$$\frac{dL_c}{dt} = -AU - AC \quad (2)$$

$$\frac{dL_r}{dt} = +AU + AC \quad (3)$$

$$\frac{dN_c}{dt} = -2AU_n - AC_n - SC_c = \frac{-2}{x^*}AU - \frac{1}{x_c}AC - SC_c \quad (4)$$

$$\frac{dN_r}{dt} = +AU_n + AC_n - SC_r = \frac{1}{x^*}AU - SC_r \quad (5)$$

c: cloud; r: rain

L: total mass; N: # concentration

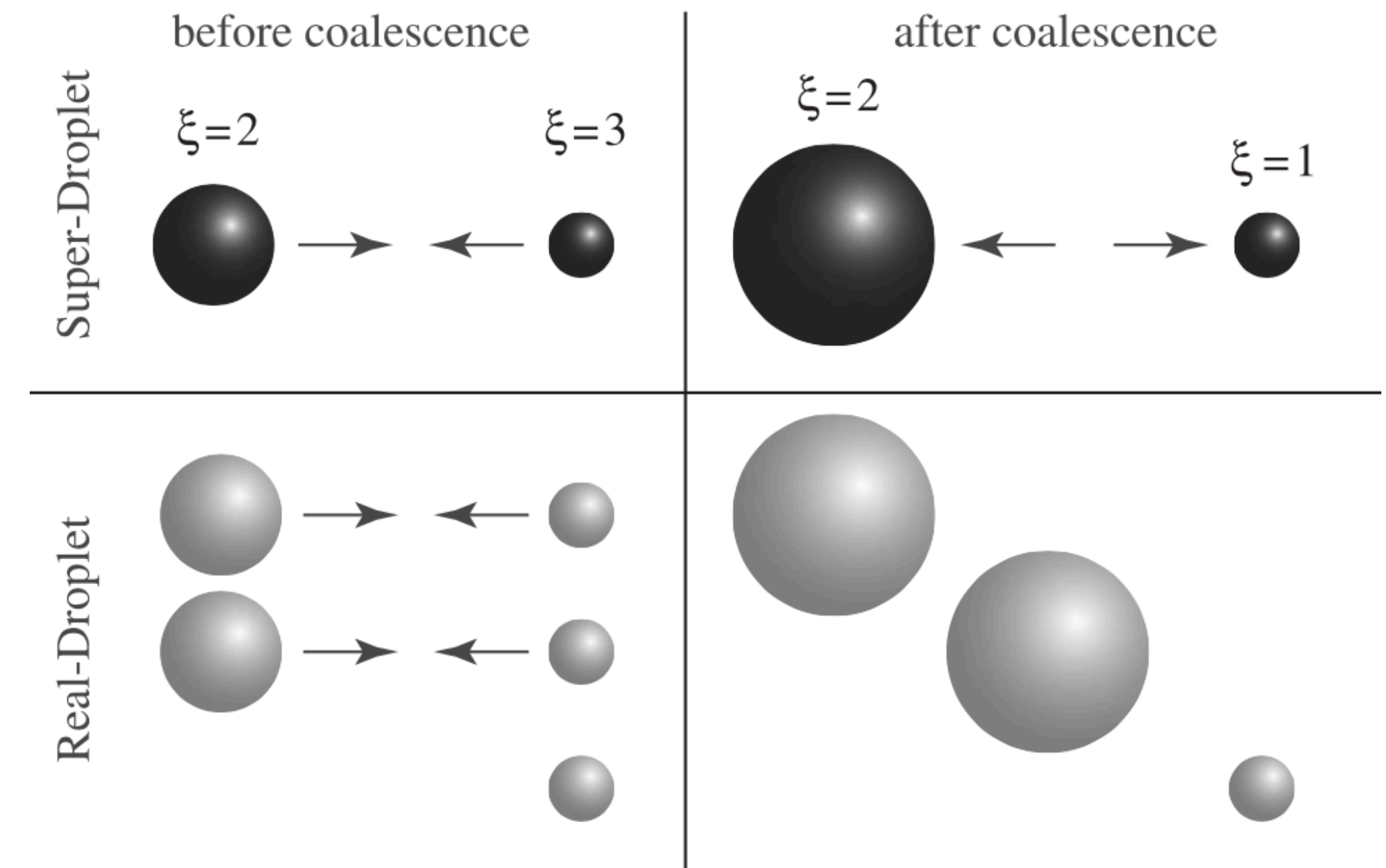
AU: auto-conversion (c → rain rate by converting)

AC: accretion (c → r rate by collision)

SC: self-collision (no c ↔ r)

Super Droplet Simulations (SDS)

- Superdroplets:
 - Multiple droplets of the same size in vicinity
 - Attributes: # of real droplets, size, position, etc.
- Setup (Lagrangian):
 - SDs advect as particles through the flow field
 - Condensation/evaporation and sedimentation are computed per-SD using standard equations.
 - Collision (stochastic): Monte Carlo random sampling of pairs of SD



Shima et al., 2009

Bulk vs. SDS

- Prognostic variables
- **Assume a gamma distribution**
- Computes AU, AC, SC rates from closed-form expressions derived by integrating the collision kernel over the assumed gamma PSD
- Cheap
- Explicit simulation
- **No assumptions of PSD**
- Computes coalescence stochastically via Monte Carlo
- More realistic and general

SuperdropNet:

- Cheap
- No PSD assumption

surrogate of H based on autoregression

$$y = \hat{H}x + n$$

stochasticity handled explicitly

Bulk moments and thermodynamics at t

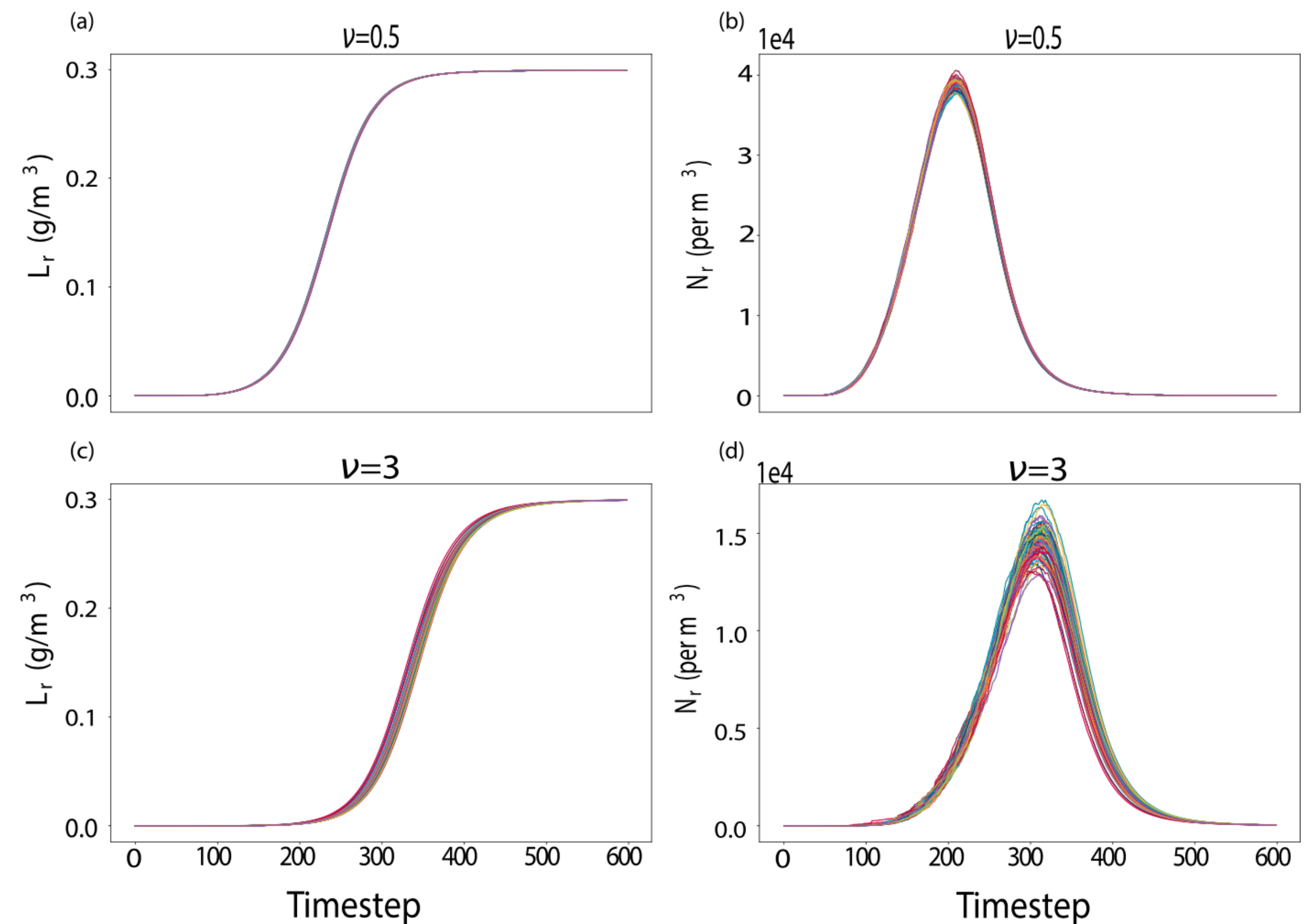
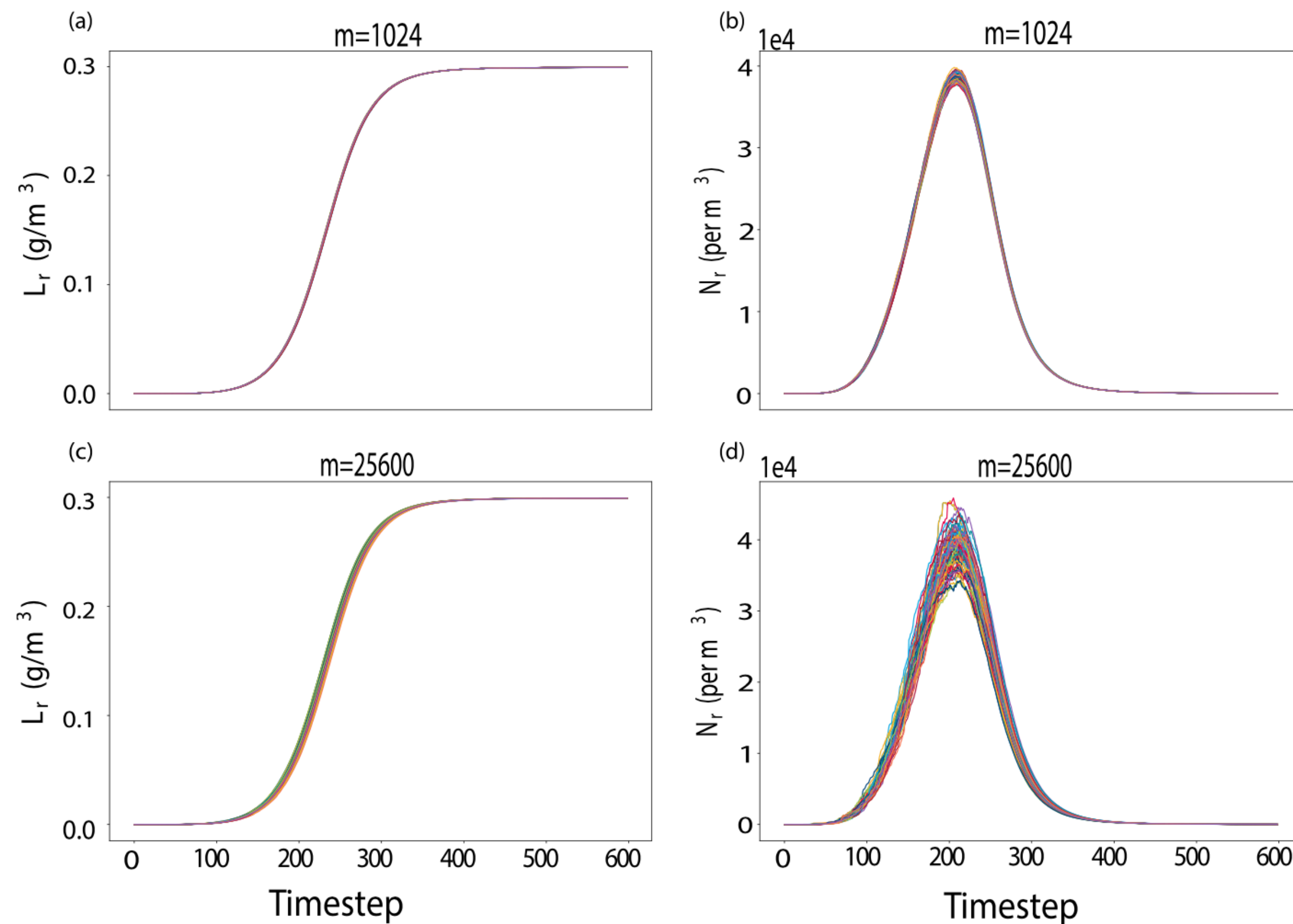
Bulk moments at t+Δt

mass & # conc. of cloud and rain particles

from SD simulations

- Stochasticity in collision
 - different results with the same initial condition
 - overfitting and instability

- To limit stochasticity
 - Chose parameters generating lower variability
 - Averaged over 100 simulations



Setup

- Constraints:

- Mass conservation: \hat{L}_r as residuals
- Irreversibility: $\hat{\Delta}L_c \leq 0$ (only in training)
- $L, N \geq 0$ (not in training)

rollout length

- Architecture:

- Fully connected
- 3 layers x 200 neurons
- ReLU

$$\mathcal{M}^{(k)}(y_t) = \overbrace{\mathcal{M} \circ \mathcal{M} \circ \dots \circ \mathcal{M}}^{k \text{ times}}(y_t) \approx y_{t+k} \quad (7)$$

$$\mathcal{M}^{(t)}(y_0) \approx y_t, \quad \forall t \quad (8)$$

$$\mathcal{M}(y_t) = y_t + h_\theta(y_t, \phi)\Delta t \approx y_{t+1} \quad (10)$$

- $k=1$: only knows 1 step ahead
 - compounding errors
- large k : loss computed at every intermediate step $t+\Delta t, t+2\Delta t, \dots, t+k\Delta t$
 - self-correction
 - but can diverge if initial condition is out-of-distribution
- Solution: “the learning curriculum” / warm start
 - Start with $k=1$, train until convergence
 - Use weights of $k=1$ to initiate training of $k=2$, repeat for $k \leq 25$

Rollout length k

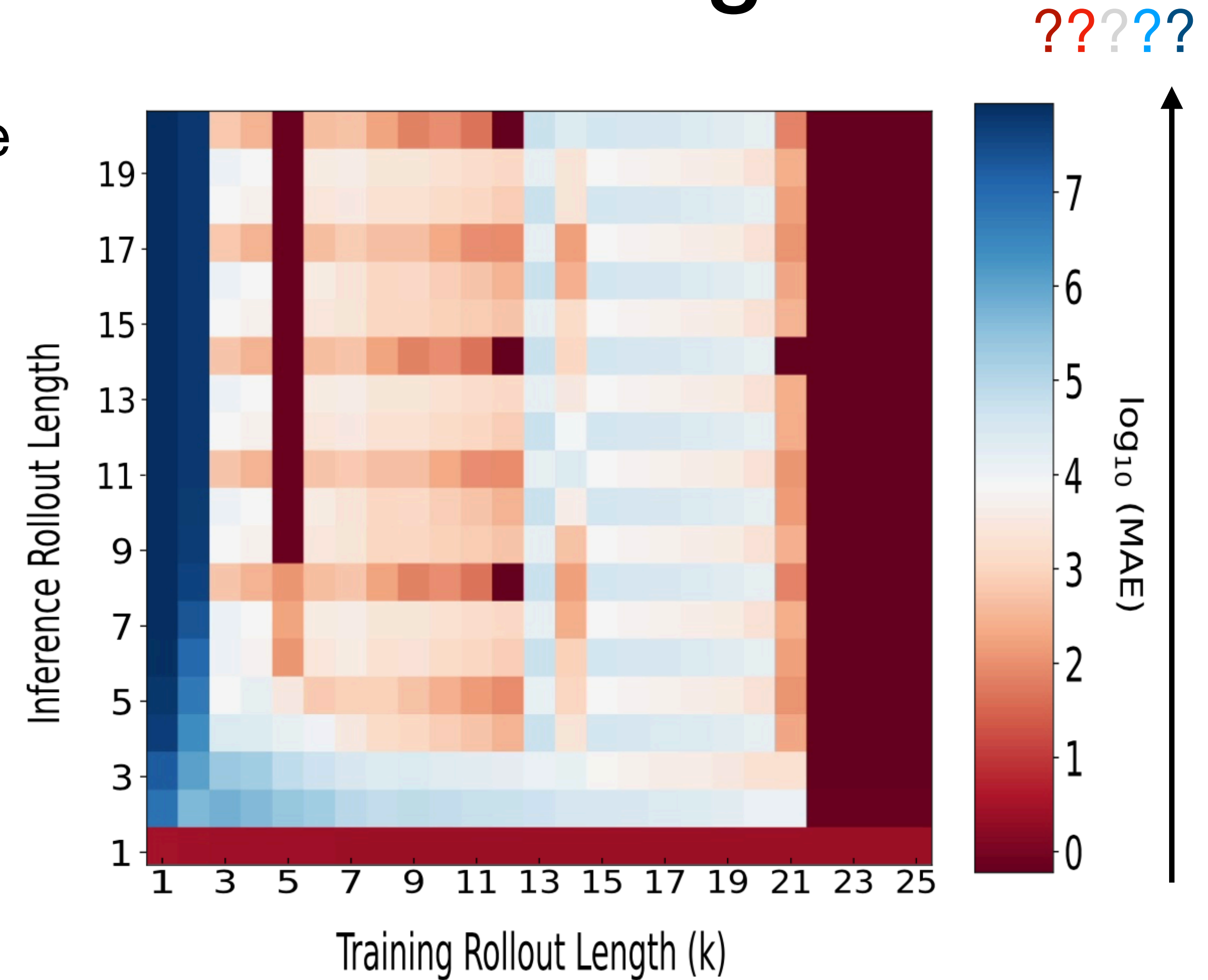


Fig. 8b

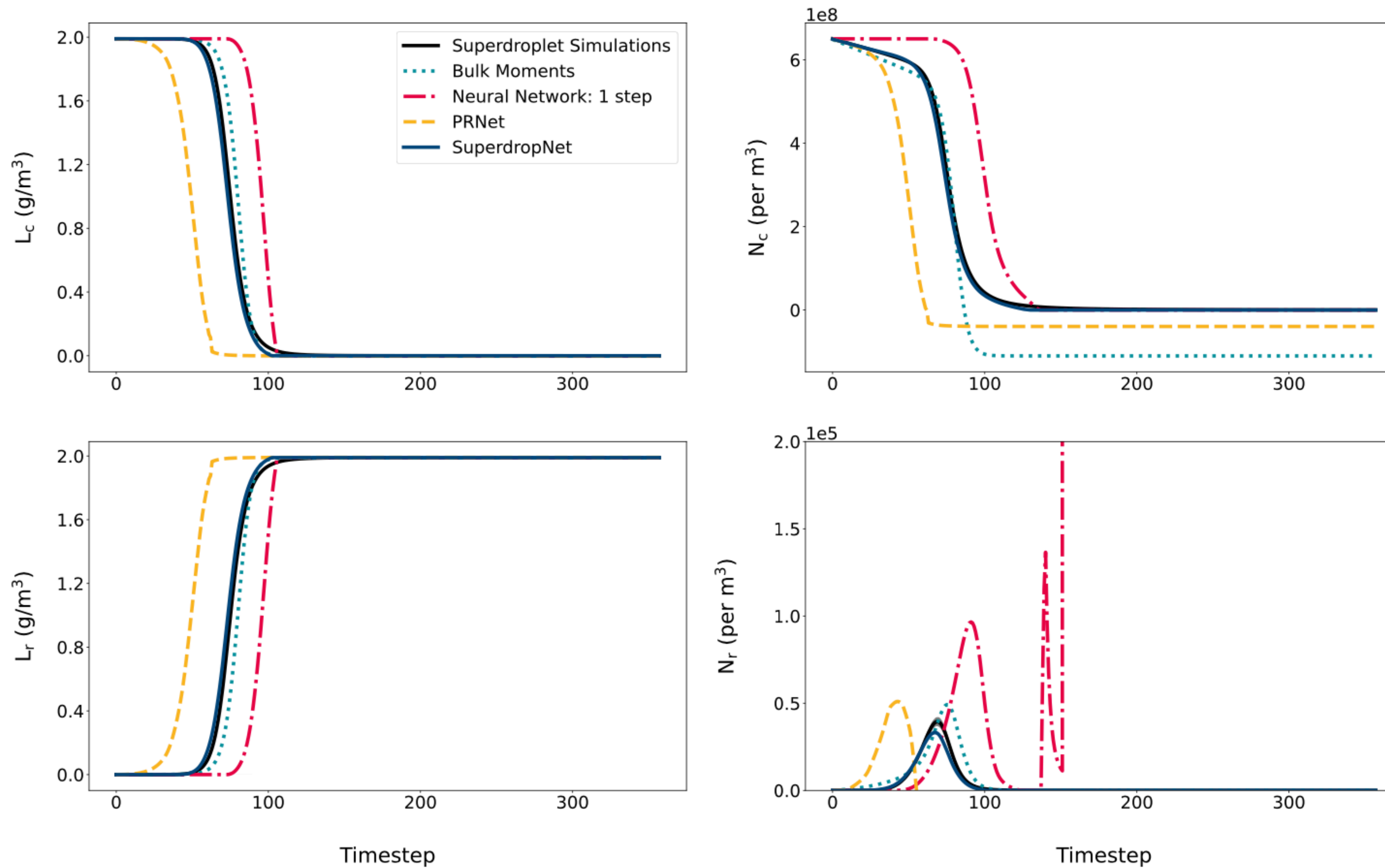


Figure 4. Superdroplet-derived bulk moments (black lines) compared to rollouts from a neural network trained to predict 1 step into the future (red-dashed lines), SuperdropNet (blue solid line), PRNet (yellow-dashed lines) and from a classical bulk moment scheme (blue-dotted lines). Results are shown for a simulation with $L_0 = 2 \text{ g/m}^3$, $r_0 = 9 \mu\text{m}$, $\nu = 0$. Shaded region indicates ± 1 standard deviation over 100 superdroplet simulations. A single time step corresponds to 20 s of simulation time.